





Techniques for Real-Time Spectral Rendering

Pedro Jose Perez¹ Nestor Monzon Adolfo Muñoz Universidad de Zaragoza

- **RGB rendering** is the most common and popular way to generate images in Computer Graphics. It **discretizes** the entire visual spectrum into three colours: **Red**, **Green**, and **Blue**, matching our visual system. This traditional RGB rendering oftenly struggles simulating **wavelength-dependent** phenomena, such as iridescence or participating media scattering, **introducing error**.
- **Spectral rendering**, on the other hand, takes into account the **entire visual spectrum** (~400 nm to ~800 nm) to synthesize images, at the cost of having to deal with many **more samples**, slower than compared to just three colours.
- While good for **offline rendering** (VFX, marketing, architecture, etc.) where time constraints are not relevant, spectral rendering's need for more samples introduces **prohibitive costs** in both memory usage and computational time for **real-time rendering** (videogames, virtual reality, etc.), where 30-120 images need to be generated **every second**.
- We devise a method that enables the usage of spectral rendering in real-time contexts minimally affecting time and memory consumption by adapting previously existing techniques, such as reflectance upsampling, into real-time contexts. We also prove its compatibility with similar rendering methods.

We take the work of Jakob and Hanika (2019) as our starting point. They upsample the entire sRGB gamut into spectral responses.

$$f(\lambda) = S(c_o\lambda^2 + c_1\lambda + c_2)$$
 function $f(c_0, c_1, c_2, w_1)$ # Evaluate polynomial for wavelength 'wl' $x = fma(fma(c_0, w_1, c_1), w_1, c_2)$ # Evaluate nonlinear map return $f(c_0, c_1, c_2, w_1)$ # Evaluate polynomial for wavelength 'wl' $f(c_0, c_1, c_2, w_1)$ # Evaluate polynomial for wavelength 'wl' $f(c_0, c_1, c_2, w_1)$ # Evaluate nonlinear map return $f(c_0, c_1, c_2, w_1)$ # Evaluate nonlinear map return $f(c_0, c_1, c_2, w_1)$ # Evaluate nonlinear map return $f(c_0, c_1, c_2, w_1)$ # Evaluate nonlinear map return $f(c_0, c_1, c_2, w_1)$

They achieve so via **lightweight look-up tables** (~6MiB) and cheap formulas that require **only 6 floating-point operations.** We recognized the potential that their technique had for real-time contexts.

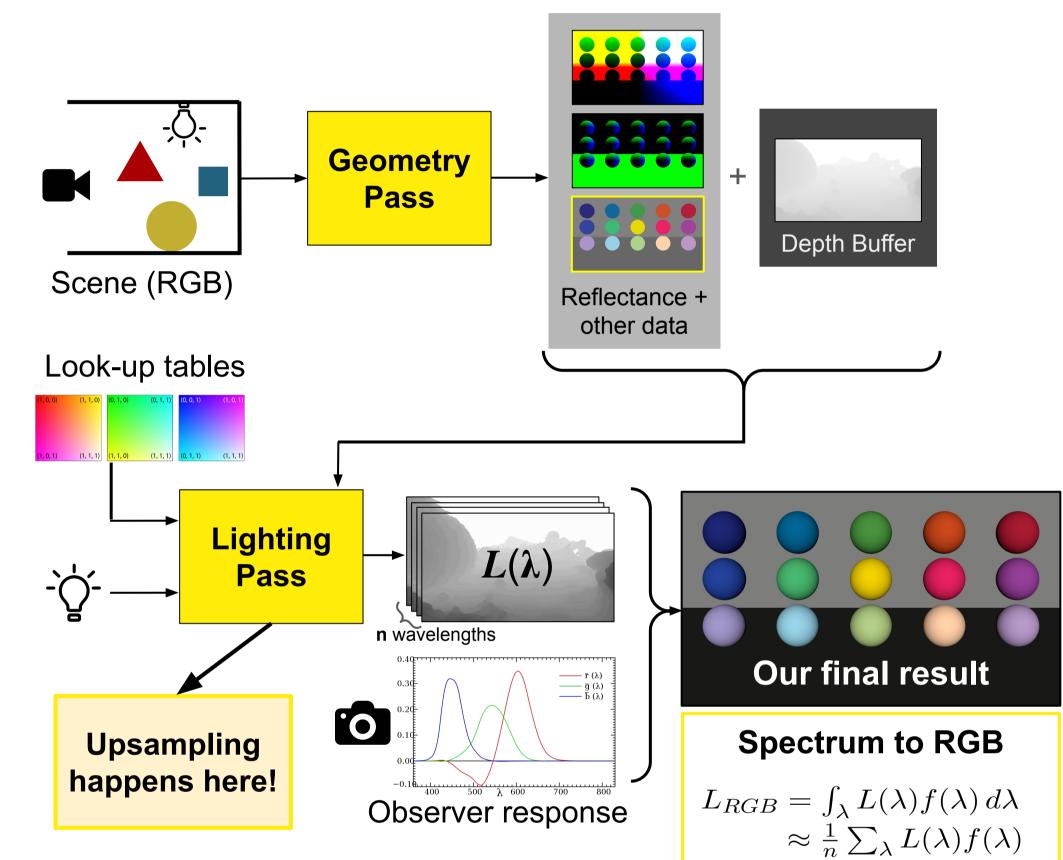






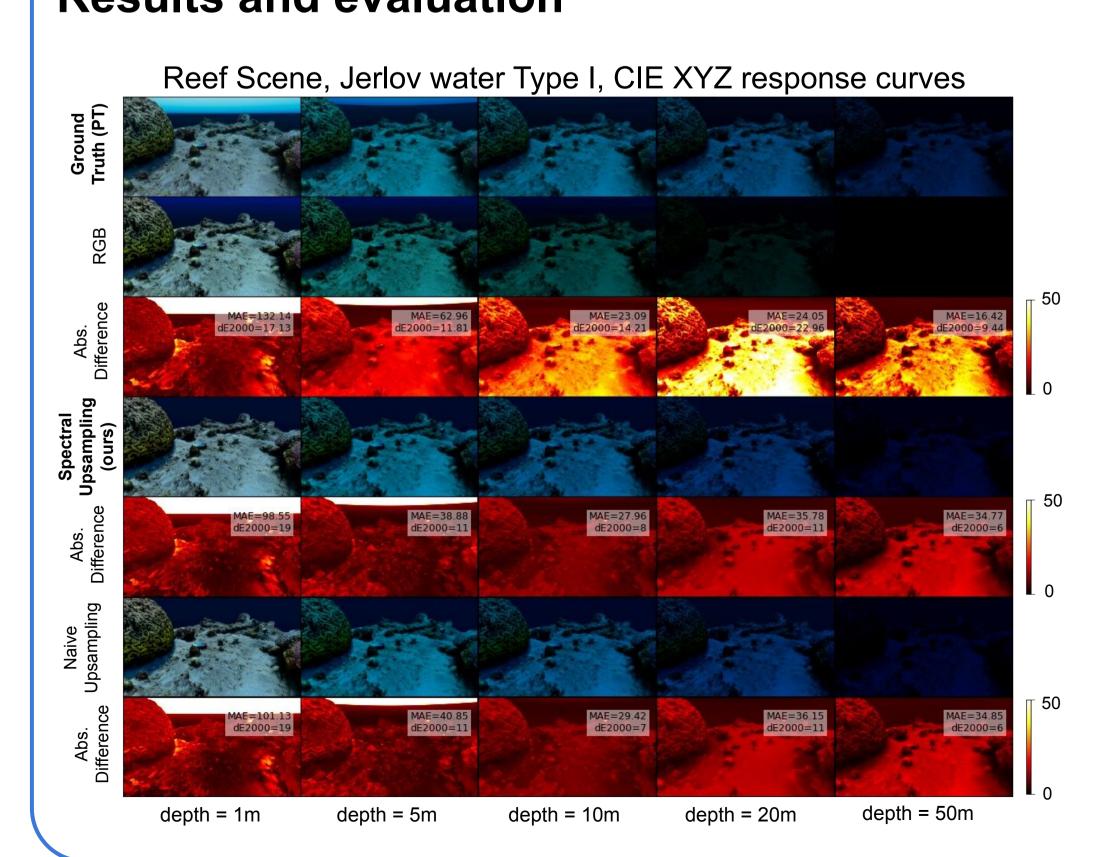
Our implementation

We implement our real-time version as an OpenGL renderer from scratch. We decided to implement a **multipass deferred pipeline**, illustrated here:



Additionally, we support the simulation of several **observer sensitivity curves**, being able to simulate several **camera types**, or the **human eye** observer. Same applies to lights, we can **load real world data** for the Spectral Power Distribution **(SPD)** of several measured light emitters. An adaptation Monzon et al.'s underwater rendering method is supported too.

Results and evaluation



- We improve error with respect to baseline comparisons in scenes with wavelength-dependent phenomena (left) and scenes with highly spiked emission spectra (below).
- We use RGB reflectance textures for spectral rendering!
- 120+ FPS for all tested use cases, real-time ready.

